NAG Toolbox for MATLAB

f08sb

1 Purpose

f08sb computes selected eigenvalues and, optionally, eigenvectors of a real generalized symmetric-definite eigenproblem, of the form

$$Az = \lambda Bz$$
, $ABz = \lambda z$ or $BAz = \lambda z$,

where A and B are symmetric and B is also positive-definite. Eigenvalues and eigenvectors can be selected by specifying either a range of values or a range of indices for the desired eigenvalues.

2 Syntax

[a, b, m, w, z, jfail, info] =
$$f08sb(itype, jobz, range, uplo, a, b, vl, vu, il, iu, abstol, 'n', n)$$

3 Description

f08sb first performs a Cholesky factorization of the matrix B as $B = U^{T}U$, when **uplo** = 'U' or $B = LL^{T}$, when **uplo** = 'L'. The generalized problem is then reduced to a standard symmetric eigenvalue problem

$$Cx = \lambda x$$
,

which is solved for the desired eigenvalues and eigenvectors. The eigenvectors of C are then backtransformed to give the eigenvectors of the original problem.

For the problem $Az = \lambda Bz$ and $ABz = \lambda z$, the eigenvectors are normalized so that

$$z^{\mathrm{T}}Bz = I$$
.

For the problem $BAz = \lambda z$ we correspondingly have

$$z^{\mathrm{T}}B^{-1}z = I.$$

4 References

Anderson E, Bai Z, Bischof C, Blackford S, Demmel J, Dongarra J J, Du Croz J J, Greenbaum A, Hammarling S, McKenney A and Sorensen D 1999 *LAPACK Users' Guide* (3rd Edition) SIAM, Philadelphia URL: http://www.netlib.org/lapack/lug

Demmel J W and Kahan W 1990 Accurate singular values of bidiagonal matrices SIAM J. Sci. Statist. Comput. 11 873–912

Golub G H and Van Loan C F 1996 Matrix Computations (3rd Edition) Johns Hopkins University Press, Baltimore

5 Parameters

5.1 Compulsory Input Parameters

1: itype – int32 scalar

Specifies the problem type to be solved.

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itype = 1

$$Az = \lambda Bz$$
.
itype = 2
 $ABz = \lambda z$.
itype = 3

 $BAz = \lambda z$.

2: **jobz – string**

If jobz = 'N', compute eigenvalues only.

If jobz = 'V', compute eigenvalues and eigenvectors.

Constraint: jobz = 'N' or 'V'.

3: range – string

If **range** = 'A', all eigenvalues will be found.

If range = 'V', all eigenvalues in the half-open interval (vl, vu) will be found.

If range = 'I', the ilth to iuth eigenvalues will be found.

Constraint: range = 'A', 'V' or 'I'.

4: uplo – string

If $\mathbf{uplo} = 'U'$, the upper triangles of A and B are stored.

if $\mathbf{uplo} = 'L'$, the lower triangles of A and B are stored.

Constraint: uplo = 'U' or 'L'.

5: a(lda,*) - double array

The first dimension of the array **a** must be at least $max(1, \mathbf{n})$

The second dimension of the array must be at least $max(1, \mathbf{n})$

The n by n symmetric matrix A.

If $\mathbf{uplo} = 'U'$, the upper triangular part of A must be stored and the elements of the array below the diagonal are not referenced.

If $\mathbf{uplo} = 'L'$, the lower triangular part of A must be stored and the elements of the array above the diagonal are not referenced.

6: b(ldb,*) - double array

The first dimension of the array **b** must be at least $max(1, \mathbf{n})$

The second dimension of the array must be at least $max(1, \mathbf{n})$

The symmetric matrix B:

if **uplo** = 'U', the leading n by n upper triangular part of **b** contains the upper triangular part of the matrix B;

if $\mathbf{uplo} = 'L'$, the leading n by n lower triangular part of \mathbf{b} contains the lower triangular part of the matrix B.

- 7: vl double scalar
- 8: vu double scalar

If range = 'V', the lower and upper bounds of the interval to be searched for eigenvalues.

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If range = 'A' or 'I', vl and vu are not referenced.

Constraint: if range = 'V', vl < vu.

- 9: il int32 scalar
- 10: iu int32 scalar

If **range** = 'I', the indices (in ascending order) of the smallest and largest eigenvalues to be returned.

If range = 'A' or 'V', il and iu are not referenced.

Constraints:

if
$$\mathbf{n} = 0$$
, $\mathbf{il} = 1$ and $\mathbf{iu} = 0$;
if $\mathbf{n} > 0$, $1 \le \mathbf{il} \le \mathbf{iu} \le \mathbf{n}$.

11: abstol – double scalar

The absolute error tolerance for the eigenvalues. An approximate eigenvalue is accepted as converged when it is determined to lie in an interval [a, b] of width less than or equal to

$$abstol + \epsilon \max(|a|, |b|),$$

where ϵ is the *machine precision*. If **abstol** is less than or equal to zero, then $\epsilon \|T\|_1$ will be used in its place, where T is the tridiagonal matrix obtained by reducing C to tridiagonal form. Eigenvalues will be computed most accurately when **abstol** is set to twice the underflow threshold $2 \times x02$ am(), not zero. If this function returns with **info** > 0, indicating that some eigenvectors did not converge, try setting **abstol** to $2 \times x02$ am(). See Demmel and Kahan 1990.

5.2 Optional Input Parameters

1: n - int32 scalar

Default: The second dimension of the array **a** The second dimension of the array **b**.

n, the order of the matrix pencil (A, B).

Constraint: $\mathbf{n} \geq 0$.

5.3 Input Parameters Omitted from the MATLAB Interface

lda, ldb, ldz, work, lwork, iwork

5.4 Output Parameters

1: a(lda,*) - double array

The first dimension of the array \mathbf{a} must be at least $\max(1, \mathbf{n})$

The second dimension of the array must be at least $max(1, \mathbf{n})$

The lower triangle (if $\mathbf{uplo} = 'L'$) or the upper triangle (if $\mathbf{uplo} = 'U'$) of \mathbf{a} , including the diagonal, is destroyed.

2: b(ldb,*) - double array

The first dimension of the array **b** must be at least $max(1, \mathbf{n})$

The second dimension of the array must be at least $max(1, \mathbf{n})$

If $info \le n$, the part of **b** containing the matrix contains the triangular factor U or L from the Cholesky factorization $\mathbf{b} = U^{\mathrm{T}}U$ or $\mathbf{b} = LL^{\mathrm{T}}$.

3: m - int32 scalar

The total number of eigenvalues found.

If range =
$$'A'$$
, $m = n$.

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